Visualizing Image Structural Similarity Using Self-Organizing Maps and HOG Features

Ernests Lavrinovics

MSc Medialogy MED08 Aalborg Univeristy, Copenhagen

Visualizing Image Latent Space Using Self-Organizing Maps and HOG Features

Ernests Lavrinovics MED08, AAU-CPH

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Introduction Image Features

- Features quantitatively describe an image
 - ORB, SIFT features use local corners to describe the image
 - Amount of features vary for resolution X
 - HOG splits an image into small cells and computes gradients
 - Amount of features are constant for resolution X
- Important because we cannot directly compare image values
 - i.e. identical images with varied lighting gives varied distance
- OpenCV is used for feature computation

Introduction Structural Similarity

- Euclidean distance of HOG descriptors $d(x, y) = \sqrt{\sum_{i=1}^{n} (y_i x_i)^2}$
- Other metrics exist
 - Structural Similarity Index (SSIM)
 - Learned Perceptual Image Patch Similarity (LPIPS)
 - Mikowski-form distance [1]



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Introduction Self-Organizing Maps (SOM)

- Algorithm originally published by T.Kohonen, sometimes referred to as *Kohonen Map*
- Unsupervised machine learning algorithm
- Used for dimensionality reduction with topological preservation
- Usually visualized as a 2D map

Introduction Self-Organizing Maps (SOM)

• Visualizing world poverty [3]



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Introduction Self-Organizing Maps (SOM)

- Training
 - 1) Initialize nodes with random values
 - 2) Take a random sample from the training data
 - 3) Find the pre-initialized node with the lowest distance to the sample. *Best Matching Unit (BMU)*
 - 4) Take the neighbourhood of BMU
 - 5) For each node in the neighbourhood, adjust them according to BMU
 - 1) New Weight = Old Weight + Learning Rate (Input Vec. Old Weights)
 - 6) Repeat from Step 2 for N iterations

Implementation Details Initializing Nodes

• Randomly samples images from the training data set

def sampleListRandomly(input : np.ndarray, n=10):
 """ Returns a list of a randomly sampled input list """
 return np.random.choice(input, size=(n, n))



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Implementation Details Training

- Shuffle the training data
- Find the BMU and update weights



Implementation Details Best-Matching Unit

• Find the index of the pre-initialized image with its closest distance with respect to HOG descriptor

```
def findBmu(self, SOM, x):
   # compare euclidean distance of each element of the SOM to the input
   # and save the index of the closest element to bmu
   distances = np.zeros((SOM.shape[0], SOM.shape[1]), dtype=np.float32)
   for width in range(len(SOM)):
        for length in range(len(SOM)):
           element = SOM[width][length].features
           # Get euclidean distance of image features
           d = np.linalg.norm(element - x.features)
           # Insert the euclidean distance into the distances array
           distances[width][length] = d
   # Get the index of the minimum distance
   min index = np.unravel index(np.argmin(distances, axis=None), distances.shape)
   # return the coordinates of the minimum distance
   return min index
```

Implementation Details Updating Weights

- Key flaw of the project
- Take a random neighbor of BMU and change it to input
- How to update neighboring nodes when using images?

```
def updateWeights(self, SOM, trainingExample, learningRate, radius, bmuCoord, step=1):
  g, h = bmuCoord
# Get neighbourhood range, prevent overshooting from edges
rWidth = (max(0, g - step), min(SOM.shape[0] - 1, g + step))
rHeight = (max(0, h - step), min(SOM.shape[1] - 1 , h + step))
# Get the random neighbour
rw = np.random.randint(low=rWidth[0], high=rWidth[1])
rh = np.random.randint(low=rHeight[0], high=rHeight[1])
# Prevent changing the BMU itself..
while (rw == g and rh == h):
  rw = random.randint(rWidth[0], rWidth[1])
  rh = random.randint(rHeight[0], rHeight[1])
# Set the image at location
SOM[rw, rh] = trainingExample
return SOM
```

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Results



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Analysis and Conclusions

- Obvious flaw in the code that does not follow the algorithm pseudo-code
- Multiple epochs can lead to duplicate images due to presenting every data point per epoch
- Different data set could be used with more separable features

Thank you!

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References

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- [2] T. Kohonen, "The self-organizing map," in Proceedings of the IEEE, vol. 78, no. 9, pp. 1464-1480, Sept. 1990, doi: 10.1109/5.58325.
- [3] http://www.cis.hut.fi/research/som-research/worldmap.html